# Shalaleh Rismani

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# **Education**

<ul> <li>Ph.D Electrical and Computer Engineering</li> </ul>	Jan 2020 – Present
McGill University	
<ul> <li>M.A.Sc Biomedical Engineering</li> </ul>	May 2017
University of British Columbia, Vancouver, BC, Canada	
$\cdot$ B.A.Sc Mechanical Engineering with Mechatronics Specialization	Nov 2013
University of British Columbia, Vancouver, BC, Canada	

# **Notable Awards**

NSERC PGS-D Scholarship	2020
We Robot 2020 Best Poster Award	2020
Les Vadasz Engineering Fellowship	2020
International Top 20 Project James Dyson Award Competition	2015
Engineers-in-Scrubs Graduate Student Award	2014
NSERC Canadian Graduate Scholarship Masters	2013
Engineers-in-Scrubs Undergraduate Student Research Award	2013
Faculty of Applied Science Graduate Award	2013
Diamond Jubilee II Medal of Canada	2013
UBC Mechanical Engineering Department Leadership Award	2013
Research In Science and Engineering (RISE) Award (Germany)	2012
Go Global International Learning Programs Award	2010
NSERC Undergraduate Student Research Award	2010

# **Highlighted research skills**

- **Qualitative research:** design, conduct and analyze interviews, focus groups and cocreation sessions for design research and science and technology studies (STS). Have used Atlas.ti, NVivo Lexalytics Semantria for content analysis.
- **Quantitative research:** design public opinion surveys, use SPSS and R to perform basic statistical analysis (t-test, ANOVA)
- **Programming:** developed Python scripts for machine learning applications (as part of 500 level intro to machine learning course), used MATLAB for controller design and data analysis
- **Communication and facilitation:** have facilitated many workshops and presented frequently on topic of AI and robot ethics. Have published academic and white papers.

# **Presentations and posters**

**S. Rismani,** A. Moon (2021) "How do AI systems fail socially?: an engineering risk analysis approach," *2021 IEEE International Symposium on Technology and Society*, Waterloo, Canada, 2021.

**S. Rismani,** A. Moon (2021) "How do AI systems fail socially? Social Failure Mode and Effect Analysis (FMEA) for artificial intelligence systems," *2021 We Robot*, Miami, Florida, 2021.

**S. Rismani,** A. Moon (2020) "Can we measure ethics of an AI system? If yes, what do we measure? How do we measure?," *2020 We Robot*, Ottawa, Canada, 2020. **\* Won best poster award** 

**S. Rismani,** A. Moon (2020) "Measuring the Ethics of an AI System" *,Montreal AI Symposium,* Montreal, Canada, 2020.

**Rismani, S,** (2019) Industry Forum Speaker, International Symposium of Industrial Electronics (ISIE) 2019, How can we design ethical AI systems? Practitioner's Perspective, Vancouver, BC.

**Rismani, S,** Moon, A (2019) Canada NextAI workshop: ORI AI Ethics Assessment Toolkit, Toronto, ON.

**Rismani, S,** Moon, A (2019) ORI AI Ethics Assessment Toolkit, Vector Research Institute, Toronto, ON.

**Rismani, S,** (2019) Women in Data Science in Stanford Conference: How can we design ethical AI systems?, Vancouver, BC.

**Rismani, S** (2019) Debated in two Women in Communication and Technology (BC Chapter) Women in Debate series. The topics:

- Can we trust AI?
- Can privacy exist in the 21<sup>st</sup> century?

**Rismani, S,** (2018) How can we design ethical AI and robotic systems? Presented at:

- BC Privacy Professionals Keynote
- IEEE WiE Conference Keynote
- ASQ Vancouver Speaker
- Norton Rose Fullbright AI Summit presenter
- FVCPAA (Fraser Valley Chartered Professional Accountant Association) Featured Speaker

**Rismani, S.** (2018) Peter Wall Scholar's Lunch Talk: Ethical Implications of Autonomous Cars, Vancouver, BC

**Rismani, S.** (2017), Playing in the Wilderness: Lessons from Creating Generation R, TECH Vancouver, BC

Rismani, S. (2017), Stories of Open Roboethics Institute. iHub Gala, Vancouver, BC

**Rismani, S.** (2017) Artificial Intelligence and Robotics – How Machine Autonomy is Changing the Way We Work? Human Factors Community of Practice, Vancouver, BC

**Rismani, S.,** Moon, A. (2017) Artificial Intelligence and Robotics – How Machine Autonomy is Changing the Way We Live? UBC Extended Learning – New Trends in Science, Vancouver, BC

**Rismani, S.** (2017) Panelist on Implications of Exponential Technology, Singularity U Event, Vancouver, BC

**Rismani, S,** Moon, A. (2017) What should a robot do? Robotics and Roboethics, BC Humanist Association, Vancouver, BC

**Rismani S,** Smith EM, Van der Loos M, Miller WC. (2017) Enhancing Engineering Education through Collaboration Across Disciplines to Create Health and Assistive Technologies. Canadian Engineering Education Association Annual Conference, Toronto, Ontario. [Workshop]

Smith EM, **Rismani S.** (2016) Collaborating to Create Assistive Technology: Cross-Cultural Dialogue. OT24-Hour Virtual Exchange. Online.

Rismani, S., Allan, G., Cheung, V. (2015) The Screw Cutter Project, Clinton Foundation, Miami, FL

# **Collaborative Reports and Documents**

- Foresight into AI Ethics Toolkit: A toolkit for creating an ethics roadmap for your AI project by Open Roboethics Institute, October 2019
- <u>Ethics Analysis of Predictive Algorithms: An Assessment Report for BC Safety Authority</u> As the System Analyst at Generation R. An AI ethics internal audit for BC Safety Authority by Generation R Consulting, July 2017
- <u>The Ethics and Governance of Lethal Autonomous Weapons Systems</u> As an assistant researcher, by Open Roboethics Institute, Nov. 2015

# **Conference Publications**

- [Accepted] **S. Rismani,** A. Moon (2021) "How do AI systems fail socially?: an engineering risk analysis approach," *2021 IEEE International Symposium on Technology and Society*, Waterloo, Canada, 2021.
- [Accepted] K. Szilagyi, J. Millar, A. Moon, **S. Rismani** (2021) "Driving into the Loop: Mapping Automation Bias & Liability Issues for Advanced Driver Assistance Systems," *2021 We Robot*, Miami, Florida, 2021.
- [On <u>arxiv</u>, submitted to ICRA 2022] S. Le Page, J. Millar, K. Bronson, **S. Rismani**, A. Moon. "Driver Perceptions of Advanced Driver Assistance Systems and Safety."
- [Accepted] A. Moon, S. Kim, **S. Rismani**, Millar J, A. van Poortvliet, C. Roome (2018) "Lessons Learned: An Ethics Roadmap for Real-Time Predictions," *presented at PAPI 2018, UK.* In press *Journal of Machine Learning Research.*

- [Accepted] **S. Rismani**, and H. F. M. Van der Loos, "Improving Needs-finding techniques for medical device development at low resource environments using Activity Theory," *2017 International Conference on Engineering Design (ICED)*, Vancouver, Canada, 2017.
- [Accepted] **S. Rismani**, P. Ostafichuck, C. Jaeger, J. Nakane, "Using a Project on Assistive Technology to Teach CAD and Rapid Prototyping", *2017 Canadian Engineering Education Association (CEEA), Toronto, Canada, 2017.*
- [Accepted] **S. Rismani**, M. Ratto and H. F. M. Van der Loos, "Use of activity theory-based need finding for biomedical device development," *Proceedings of the 2016 38th Annual International Conference of the IEEE Engineering in Medicine and Biology Society (EMBC)*, Orlando, FL, 2016, pp. 4341-4344.
- [Accepted] **S. Rismani**, and H. F. M. Van der Loos, " The competitive advantage of using 3dprinting in low-resource healthcare settings," *Proceedings of the 2015 International Conference on Engineering Design (ICED)*, Milan, Italy, 2015.
- [Accepted] **S. Rismani**, G. Allan, V. Chung, D. Wilson, "Applying the Biodesign innovation process: Addressing the inadequate supply of surgical screws in the developing world," *Proceedings of the 2014 IEEE Conference on Healthcare Innovation and Point-of-Care Technologies*, Seattle, DC, 2014.

# **Journal Publications**

- [Accepted] Moon, A., **Rismani, S**. & Van der Loos, H.F.M. Ethics of Corporeal, Co-present Robots as Agents of Influence: a Review. Curr Robot Rep (2021). https://doi.org/10.1007/s43154-021-00053-6
- [Accepted] EM. Smith, S. **Rismani S**, WB. Mortenson, A. Mihailidis, WC. Miller. (2017) "*A Chance to Try*": *Shared Control for Powered Wheelchair Assessment and Training*. American Journal of Occupational Therapy.

# Thesis

Use of activity theory as the basis for a novel needs-finding technique for medical device development in low-resource environments

# **Research and Work Experience**

#### Research assistant,

Responsible Autonomy and Intelligent Systems Ethics (RAISE lab), Montreal, Canada

- Lead and conduct a scoping review on how the ethics of an AI system is being evaluated
- Lead the study on developing an ontology of occupations in the budding AI ethics industry
- Lead a project on framing ethical and social failures for ML systems and how we can assess/control for them
- Mentor and co-supervise undergraduate research assistants

### Director, design research and education

Open Roboethics Institute, Vancouver, Canada

- Lead the development of ORI AI ethics assessment toolkit
- Present at various venues about the mission and projects of ORI

Apr 2017 – Present

Jan 2020 – Present

MASc. 2017

• Create new partnerships and research opportunities for ORI

#### AI ethics operationalization research assistant,

Mila, Montreal, Canada

- Conduct organizational research to understand the existing perspectives towards implementation of AI ethics practices
- Assist in developing appropriate tools that researchers within Mila could use

### **Chief Innovation Officer/System Analyst**

Generation R Consulting, Vancouver, Canada

- Develop a framework to identify ethical and social implications of implementing automation initiatives in companies
- Perform ethics assessment for organizations deploying predictive algorithms

#### **Research Assistant**

Collaborative Advanced Robotics and Intelligent Systems (CARIS) Lab, Vancouver, Canada

- Develop an extension to the Cultural Historical Activity Theory to use for needs finding in medical device development
- Facilitate workshops and study the use of this design technique by design teams
- Conduct interviews with technology users for various project and analyze qualitative data

#### **Design Research Assistant**

Rehabilitation Research Lab, GF Strong Rehabilitation Center, Vancouver, Canada

- Co-interview and host prototyping and testing sessions with occupational therapists
- Assist in analyzing and synthesizing the data
- Provide design recommendations

### **Engineers-in-Scrubs Research Assistant**

University of British Columbia, Vancouver, Canada

- Use grounded theory principles to analyze feedback from nurses and surgeons
- Develop design needs and requirements based on the analysis for medical devices used in international orthopedic surgery

#### **RISE Engineering Research Assistant**

Laboratory for Machine Tools and Production Engineering, RWTH, Aachen, Germany

- Design a program to control the SCHUNK robotic gripper using Simulink and MATLAB
- Develop ideas for using the force data from the tactile sensors of the gripper to ease the assembly process

#### Data Analyst

Cellula Robotics, Vancouver, Canada

Jun 2014 – Jan 2015

May 2013 – Aug 2013

May 2012 – Aug 2012

Jan 2012 – Apr 2012

Sep 2013 – Mar 2017

Oct 2021 – Present

Apr 2017 – Jan 2019

• Use MATLAB to analyze a set of position and pressure data from an undersea robotic excavator to calculate the specific energy and determine the shape of the excavated region.

#### **Design Approval Organization Engineering Student**

Heli-One (Delta, Canada)

• Develop an online catalog for all major design modifications using Adobe Dreamweaver by collecting expert opinion, complete several small design modifications to the helicopter

**Undergraduate Research Assistant** May 2010 – Aug 2010 Collaborative Advanced Robotics and Intelligent Systems (CARIS) Lab, Vancouver, Canada

• Develop anthromimetic feedback on the wrist of an industrial robotic arm such that the human-robot collaborator can more intuitively understand the joint limits of the arm.

# **Teaching and Curriculum Design Experience**

**Curriculum designer assistant ECSE 557, Introduction to Ethics of AI Systems** McGill University, Canada

• Assist in the design and development of the course content and lead in developing five of the tutorials for students

#### **Adjunct Professor**,

**APSC 100/100 Introduction to Engineering Design** University of British Columbia, Canada

- Facilitate and lead the design studios for seven different modules that are part of the firstyear engineering design course at UBC
- Connect the students learning with other

### Adjunct Professor,

**UBC Vancouver Summer Program** University of British Columbia, Canada

• Design, teach and manage a 3-credit roboethics course during the 4-week Vancouver Summer Program offered to 60 international students who speak English as their second language

#### **AI Ethics and STEM Teacher**

Brainboost, Vancouver, Canada

- Work on the STEM subjects with students from the age of 12-19 who have different learning abilities and have had difficulties in the regular school system
- Teach an AI/robot ethics course to k-12

Sep 2018 – Apr 2021

May 2018 - Aug 2018

June 2021- Present

Sep 2010 – Dec 2010

Jan 2018 – Mar 2020

assistive technologies as part of a new first-year engineering design course		
<b>Community-based experiential learning coordinator</b> Center for Community-Engaged Learning, University of British Columbia	May 2016- Apr 2017	
• Create and coordinate experiential learning experience for 2 <sup>nd</sup> and 3 <sup>rd</sup> and mechanical engineering courses	<sup>d</sup> year civil, electrical	
<b>Graduate teaching assistant</b> Mechanical Engineering Department, University of British Columbia	Jan 2014 – Apr 2016	
• Prepare teaching material and deliver lab and tutorials for 2 <sup>nd</sup> year m students for a fluid mechanics lab and a design course	echanical engineering	
<b>Peer-assisted study session (PASS) leader and coordinator</b> Center for Student Involvement and Careers, University of British Columbia	Jan 2013 – Apr 2015	
• Design and deliver PASS sessions for first-year engineering math and following the supplemental instruction model, coordinate and train a	physics courses group of PASS leaders	
Design Projects		
Screw Cutter (UBC, Vancouver and Kampala, Uganda)	Sep 2013 – Mar 2017	
<ul> <li>Understand the inventory needs of orthopedic wards in developing countries, particularly investigating the needs of the Mulago National Hospital in Kampala, Uganda</li> <li>Develop prototypes and detailed design for the Screw Cutter within the team</li> <li>Conduct user testing at Mulago National Hospital</li> </ul>		
MUSE Chair (UBC, Vancouver)	Sep 2012 – May 2013	
<ul> <li>Design user interfaces for controlling music that can be retrofittable of user interface is designed for dementia patients and the elderly.</li> <li>Build the prototypes using 3D printers and water-jet cutters.</li> <li>Design and run tests with elderly</li> </ul>	onto any armchair. The	
Trail Rider (UBC, Vancouver)	Sep 2011 – Dec 2011	

• Work collaboratively with the British Columbia Mobility Opportunity Society (BCMOS) to understand the needs of the Trail Rider users. BCMOS is a non-profit organization that enables people with disabilities to experience outdoors by providing resources such as the TrailRider, a human-powered single-wheel device that takes people with disabilities to hiking trails.

Jun 2015- Apr 2017

**Curriculum designer** First Year Chair Team, University of British Columbia

• Lead the design and development of all the content for a 3-week module on designing

# Trail Rider (UBC, Vancouver)

• Develop conceptual detail designs for a power-assist, suspension mechanism, and ergonomics adjustments for the redesign.

#### Solar Water Heater (Tsomanotik, Mexico)

Jul 2011 – Aug 2011

- Complete a technical project regarding alternative energy in Tsomanotik, a non-profit organization situated at Tzimol, a small town in the most southern state of Mexico, Chiapas.
- Analyze and study the existing running water system and solar water heaters to identify the problems.
- Design, build and install three human-powered mechanisms for raising water to a higher level tank which increased the inlet pressure of the water heater. The three designs were a bicycle pump, a hand pump and a pulley system.

# **Volunteer and Service Experience**

VP external communication	
Graduate Engineering Equity Committee (GEEC)	Jan 2020 – present
<b>Director, teacher, choreographer</b> Chichaklar Dance Company	Jun 2009 – present
<b>Executive member</b> Open Roboethics Initiative, Vancouver, Canada	Apr 2013 – Mar 2017
<b>VP of Communication</b> Mechanical Engineering Graduate Association	Jan 2014 – Dec 2015
<b>Event coordinator</b> Women in Engineering, UBC Student Development	Apr 2011- Apr 2013
<b>Team co-lead</b> Global Engineering, Engineers without Borders UBC Chapter	Apr 2011- Apr 2013